



# MECA0525 RIDE & COMFORT

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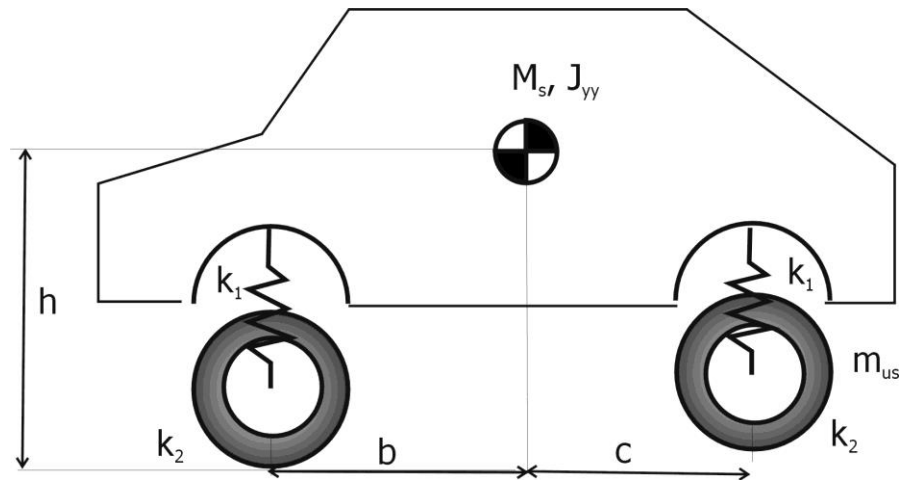
## Exercise 1:

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Bounce, pitch and wheel hop  
frequencies

# Exercise 1

- A car is characterized by
  - Vehicle body
    - Mass  $M=1300$  kg
    - Inertia  $J_{yy}=1000$  kg.m<sup>2</sup>
    - $L=3,00$  m;
    - $b=1,5$  m;  $c=1,5$  m
  - Suspension stiffness:
    - $K_s= 40$  kN/m on each axle
    - $K_t= 400$  kN per tire
  - Unsprung mass
    - $M_{us}=30$  kg per wheel





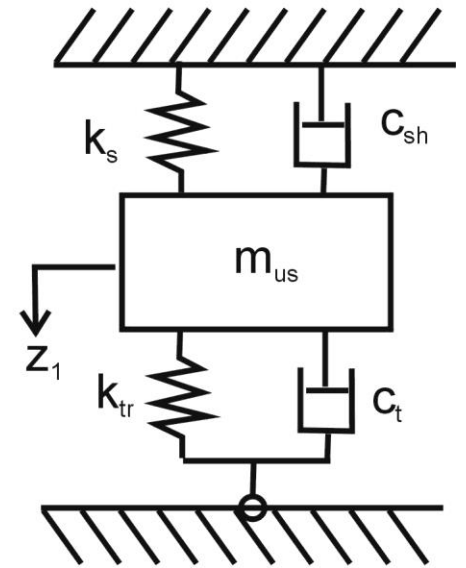
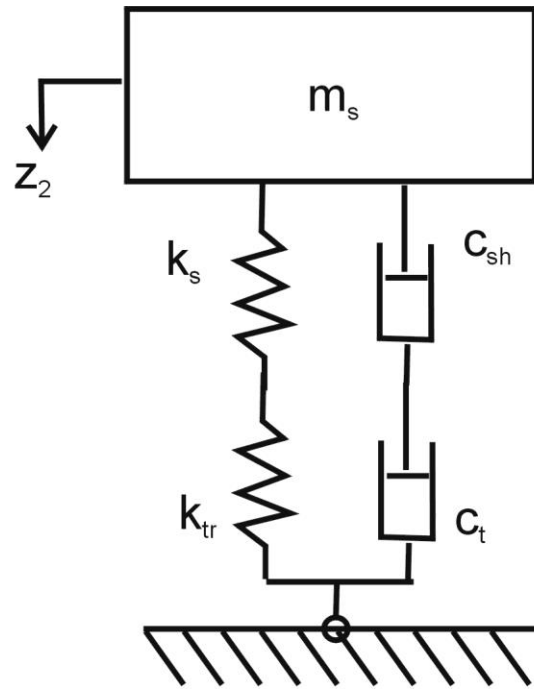
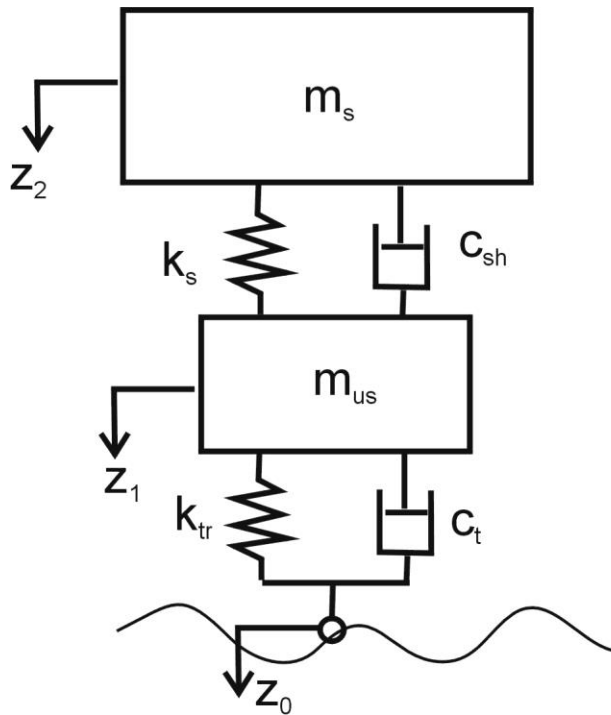
# Exercise 1

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- It asked to determine:
  - To calculate the eigenfrequencies (exact and approximate) for the wheel hop and the body mode
  - To calculate the eigenfrequency of the pitch and bouncing mode

# Exercise 1

- Approximate and "exact" body and wheel hop frequencies





# Exercise 1

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- Approximate body and wheel hop frequencies

- Body frequency

$$f_{Body} = \frac{1}{2\pi} \sqrt{\frac{k^*}{m_s}}$$

$$\frac{1}{k^*} = \frac{1}{k_s} + \frac{1}{k_t} = \frac{1}{20 \cdot 10^3} + \frac{1}{400 \cdot 10^3}$$

$$k^* = 19,048 \cdot 10^3 \text{ [N/m]}$$

$$f_{Body} = \frac{1}{2\pi} \sqrt{\frac{19048}{1300/4}} = 1,2184 \text{ [Hz]}$$

$$k_s = \frac{40 \cdot 10^3}{2} = 20000 \text{ [N/m] !!!}$$

$$m_s = 1300/4 = 325 \text{ [kg]}$$

- Wheel hop frequency



# Exercise 1

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- Approximate body and wheel hop frequencies
  - Body frequency
  - Wheel hop frequency

$$f_{Wheel} = \frac{1}{2\pi} \sqrt{\frac{k_s + k_t}{m_{us}}}$$

$$k_s + k_t = 200 \cdot 10^3 + 20 \cdot 10^3 = 220000 \text{ [N/m]} \quad m_{us} = 30 \text{ [kg]}$$

$$f_{Wheel} = \frac{1}{2\pi} \sqrt{\frac{220000}{30}} = 13,62 \text{ [Hz]}$$



## Exercise 1

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- “Exact” body and wheel hop frequencies

$$\omega_{n1}^2 = \frac{B_1 - \sqrt{B_1^2 - 4A_1C_1}}{2A_1} \quad \omega_{n2}^2 = \frac{B_1 + \sqrt{B_1^2 - 4A_1C_1}}{2A_1}$$

$$A_1 = m_s m_{us}$$

$$B_1 = m_s k_s + m_s k_{tr} + m_{us} k_s$$

$$C_1 = k_s k_{tr}$$

$$A_1 = m_s m_{us} = 325 \cdot 30 = 9750 \text{ kg}^2$$

$$\begin{aligned} B_1 &= m_s k_s + m_s k_{tr} + m_{us} k_s \\ &= 325 \cdot 20 \cdot 10^3 + 325 \cdot 200 \cdot 10^3 + 30 \cdot 20 \cdot 10^3 = 72,10 \cdot 10^6 \end{aligned}$$

$$C_1 = k_s k_{tr} = 200 \cdot 10^6 \cdot 20 \cdot 10^6 = 4,0 \cdot 10^9$$





## Exercise 1

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- “Exact” body and wheel hop frequencies

$$\rho = \sqrt{B_1^2 - 4A_1C_1} = 71.009928 \cdot 10^6$$

- Body frequency

$$\omega_{n1}^2 = \frac{B_1 - \rho}{2A_1} = 55,9010$$

$$\omega_{n1} = 7,4767$$

$$f_{n1} = \frac{1}{2\pi} \omega_{n1} = 1,1899 [Hz]$$

- Wheel hop frequency

$$\omega_{n2}^2 = \frac{B_1 + \rho}{2A_1} = 7,3389 \cdot 10^3$$

$$\omega_{n2} = 85.6677$$

$$f_{n2} = \frac{1}{2\pi} \omega_{n2} = 13,6344 [Hz]$$



# Exercise 1

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- Calculate the approximate frequency for the vehicle body bounce and pitch motion
- Reminder

$$\begin{cases} m_s \ddot{z} + k_f (z - l_f \theta - z_f) + k_r (z + l_r \theta - z_r) = 0 \\ I_y \ddot{\theta} - k_f l_f (z - l_f \theta - z_f) + k_r l_r (z + l_r \theta - z_r) = 0 \end{cases}$$

■ or

$$\begin{cases} \ddot{z} + D_1 z + D_2 \theta = 0 \\ \ddot{\theta} + D_3 \theta + \frac{D_2}{r_y^2} z = 0 \end{cases}$$
$$D_1 = \frac{1}{m_s} (k_f + k_r)$$
$$D_2 = \frac{1}{m_s} (k_r l_r - k_f l_f)$$
$$D_3 = \frac{1}{I_y} (k_f l_f^2 + k_r l_r^2)$$



# Exercise 1

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- Calculate the approximate frequency for the vehicle body bounce and pitch motion

$$D_1 = \frac{1}{m_s} (k_f + k_r) = \frac{40 \cdot 10^3 + 40 \cdot 10^3}{1300} = 61,538$$

$$D_2 = \frac{1}{m_s} (k_r l_r - k_f l_f) = \frac{40 \cdot 10^3 \cdot 1,5 - 40 \cdot 10^3 \cdot 1,5}{1300} = 0$$

$$D_3 = \frac{k_f l_f^2 + k_r l_r^2}{I_y} = \frac{40 \cdot 10^3 \cdot 1,5^2 + 40 \cdot 10^3 \cdot 1,5^2}{1000} = 180$$

- Since  $D_2=0$ , the two modes are uncoupled, and they have the simplified expressions

$$\omega_{n1} = \sqrt{D_1} = 13,4160$$

$$\omega_{n2} = \sqrt{D_3} = 7,8446$$

$$f_{n1} = \frac{1}{2\pi} \omega_{n1} = 1,2485 \text{ [Hz]}$$

$$f_{n2} = \frac{1}{2\pi} \omega_{n2} = 2,1353 \text{ [Hz]}$$



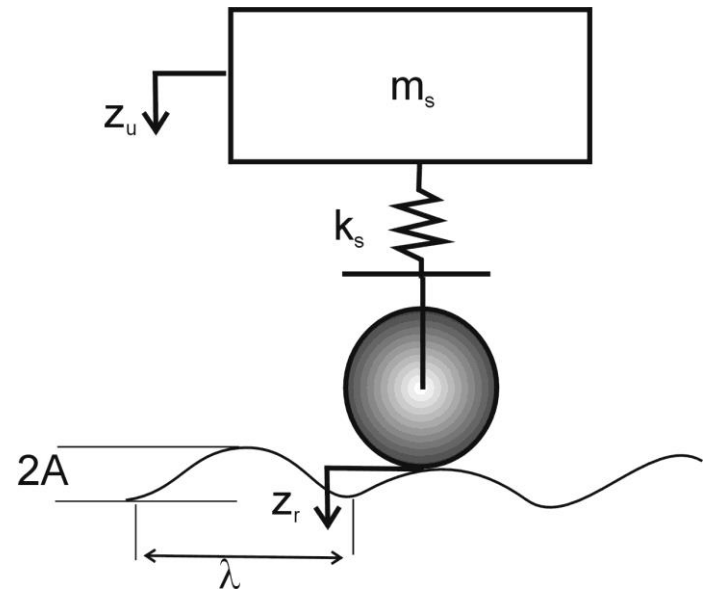
## Exercise 2:

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Establish a transfer function of the suspension system

## Exercise 2

- Derive the expression of the transfer function from road vertical excitation [m] to driver vertical acceleration [ $\text{m/s}^2$ ] for the following simplified suspension model.
- Derive the transfer function from road vertical excitation to road contact force [N]
- Calculate the road excitation frequency [Hz] when the vehicle drives at 50 km/h
  - $\lambda = 2$  m
  - $2A = 0,1$  m



- $M_s = 300$  [kg]
- $K = 20$  [kN/m]
- The tire is very stiff, and its mass is negligible

## Exercise 2

- The differential equation of the system writes

$$m_s \ddot{z}_u(t) + k_s(z_u(t) - z_r(t)) = M_s g$$

- Passing in frequency domain, one gets

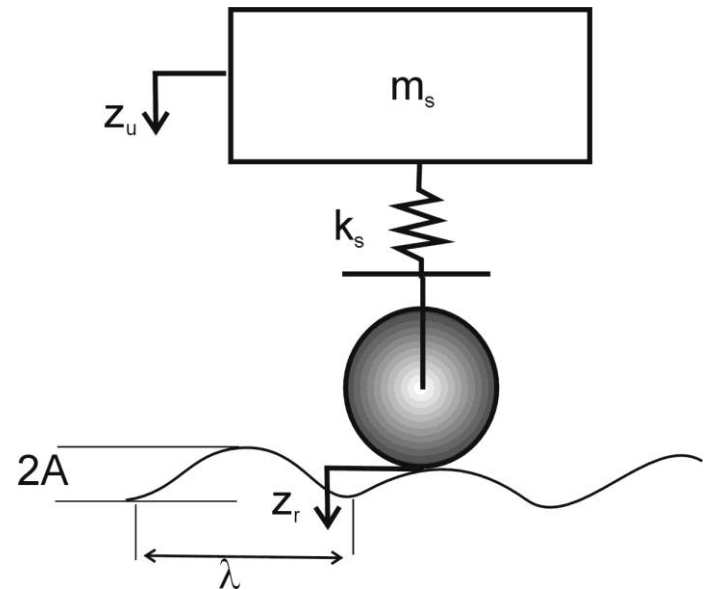
$$z_u(t) = Z_u e^{j\omega t}$$

$$z_r(t) = Z_r e^{j\omega t}$$

$$\ddot{z}_u(t) = -\omega^2 Z_u e^{j\omega t}$$

- So the homogeneous equation becomes

$$-\omega^2 m_s Z_u + k_s(Z_u - Z_r) = 0$$



## Exercise 2

- The transfer function can be obtained in the following way

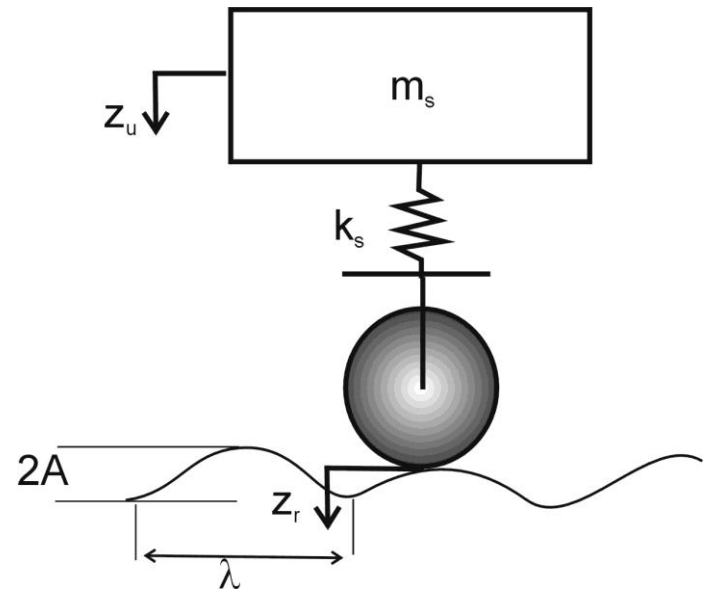
$$(-\omega^2 m_s + k_s) Z_u = k_s Z_r$$

- Or

$$H_{Z_r \rightarrow Z_u} = \frac{Z_u}{Z_r} = \frac{k_s}{-\omega^2 m_s + k_s}$$

- To obtain the transfer function of acceleration

$$H_{Z_r \rightarrow \ddot{Z}_u} = \frac{-\omega^2 Z_u}{Z_r} = \frac{-\omega^2 k_s}{-\omega^2 m_s + k_s} = \frac{\omega^2 \omega_n^2}{\omega^2 - \omega_n^2} = \frac{1}{\frac{1}{\omega_n^2} - \frac{1}{\omega^2}}$$





## Exercise 2

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- Derive the transfer function from road vertical excitation [m] to the road contact force [N]
  - Road contact force

$$F_{rz} = m_{us}\ddot{z}_{us} + mg + k_s(z_r(t) - z_u(t))$$

$$\Delta F_{rz} = k_s(z_r(t) - z_u(t))$$

- Transfer function between variation of vertical force and road vertical variation

$$H_{Z_r \rightarrow \Delta F_{zr}} = k_s \frac{Z_r - Z_u}{Z_r} = k_s \left( 1 - \frac{Z_u}{Z_r} \right)$$

- since

$$H_{Z_r \rightarrow Z_u} = \frac{Z_u}{Z_r} = \frac{k_s}{-\omega^2 m_s + k_s}$$





## Exercise 2

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- Transfer function between variation of vertical force and road vertical variation

$$H_{Z_r \rightarrow \Delta F_{zr}} = k_s \frac{Z_r - Z_u}{Z_r} = k_s \left( 1 - \frac{k_s}{-\omega^2 m_s + k_s} \right)$$

$$H_{Z_r \rightarrow \Delta F_{zr}} = k_s \frac{-\omega^2 m_s + k_s - k_s}{-\omega^2 m_s + k_s} = \frac{-k_s m_s \omega^2}{-\omega^2 m_s + k_s}$$

$$H_{Z_r \rightarrow \Delta F_{zr}} = \frac{-k_s \omega^2}{\omega_n^2 - \omega^2}$$



## Exercise 2

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- Calculate the road excitation frequency [Hz] when the vehicle travels at  $V=50$  km/h

- The spatial wavelength is

$$\lambda_s = 2 \text{ [m]}$$

- The spatial frequency [cycle/m]

$$f_s = \Omega = n = 1/\lambda_s = 0,5 \text{ [cycle/m]}$$

- The Velocity is

$$V = \frac{50 \text{ km/h}}{3,6} = 13,8889 \text{ [m/s]}$$

- The time frequency is

$$f_t = \Omega \cdot V = n \cdot V$$
$$f_t = 0,5 \cdot 13,8889 = 6,9444 \text{ [Hz]}$$

- The angular time frequency

$$\omega = 2\pi f_t = 43,6333 \text{ [rad/s]}$$



## Exercise 2

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- When driving under given conditions, calculate the acceleration level at the driver's head

$$H_{Z_r \rightarrow \ddot{Z}_u} = \frac{-\omega^2 k_s}{-\omega^2 m_s + k_s} = \frac{\omega^2 \omega_n^2}{\omega^2 - \omega_n^2}$$

$$\omega = 2\pi f_t = 2\pi 6,9444 [Hz] = 43,6333 [rad/s]$$

$$\omega_n = \sqrt{\frac{k_s}{m_s}} = \sqrt{\frac{20 \cdot 10^3}{300}} = 8,1650 [rad/s] \quad f_n = \frac{1}{2\pi} \omega_n = 1,2995 [Hz]$$

$$|H_{Z_r \rightarrow \ddot{Z}_u}| = \left| \frac{43,6333^2 \cdot 8,1650^2}{43,6333^2 - 8,1650^2} \right| = 69,0864 \quad Z_r = \frac{A}{2} = \frac{0,1}{2} = 0,05 [m]$$

$$|\ddot{Z}_u| = |H_{Z_r \rightarrow \ddot{Z}_u}| |Z_r| = 69,0864 \cdot 0,05 = 3,4543 [m/s^2]$$

$$RMS(|\ddot{Z}_u|) = \frac{|\ddot{Z}_u|}{\sqrt{2}} = 2,4425$$



## Exercise 2

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- When driving under given conditions, calculate road contact force [N] with respect to the given road excitation

$$H_{Z_r \rightarrow \Delta F_{zr}} = \frac{-k_s \omega^2}{\omega_n^2 - \omega^2}$$

$$\omega = 43,6333 \text{ [rad/s]} \quad \omega_n = 8,1650 \text{ [rad/s]}$$

$$|H_{Z_r \rightarrow \Delta F_{zr}}| = \left| \frac{20 \cdot 10^3 \cdot 43,6333^2}{8,1650^2 - 43,6333^2} \right| = 20725,7490 \text{ [N]}$$

$$Z_r = \frac{A}{2} = \frac{0,1}{2} = 0,05 \text{ [m]}$$

$$|\Delta F_{zr}| = |H_{Z_r \rightarrow \Delta F_{zr}}| |Z_r| = 20.725,7490 \cdot 0,05 = 1036,2874 \text{ [N]}$$