INTRODUCTION TO VEHICLE SAFETY AND CRASHWORTHINESS

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Sustainability in automotive industry



- Vehicle safety and more generally road safety is intrinsically a part of a sustainable automotive industry
- Road safety has a considerable impact on society
 - Emotional impact of people who experience the accidents
 - Economical impact of dead or wounded people
 - Cost on health care system
 - Loss on investment on educated young people who are the future of the society and economy
- Road safety must be considered as a high priority constraint of the development of automobile systems and road infrastructures





Fardier of Cugnot: First road accident in 1770

- Vehicle safety is a societal issue.
 - Worldwide, 1 person dies on the road every minutes
 - The cost of the road accident is estimated to 3% of world GDP, that is about € 1 billion
 - High emotional cost
- From very early, car manufacturers and public operators have paid attention to road accidents and fatalities.
- Different technical and educational solutions have been tailored, but the challenge is still important.
- One major factor: 70 to 90% of the accidents are due to human errors.
- With the weight reduction and fuel consumption the problem becomes even more critical.

Road death per million inhabitants in EU



2010 2017

Source: 2010 data: European Commission's press release, 10 April 2018; 2017 data: European Commission, Road safefy 2017 – How is your country doing?, November 2018.



WHO CAUSES CAR ACCIDENTS?

Allianz 🕕

Percentage of at-fault accidents on all accidents with injuries (2006)





EU White paper

- In 2000 the EU commission stressed an ambitious program in order to reduce the fatalities in roads accidents by a factor 2
- Situation in 2000
 - 41000 fatalities per year in EU
 - Total cost of road accidents: 2% of the GDP
 - Expenses for preventing < 5% of the this cost
- Tools to achieve the target
 - To promote the new technologies
 - Faces, black boxes,
 - To harmonize the penalties
 - Speed limits, alcohols...

Fatalities in road accidents in EU



Targets for 2030

	Indicator	Guiding objective
Decarbonization	Energy efficiency: urban passenger transport	+80% *
	Energy efficiency: long-distance freight transport	+40% *
	Renewables in the energy pool	Biofuels: 25% Electricity: 5%
Reliability	Reliability of transport schedules	+50% *
	Urban accessibility	Preserve Improve where possible
Safety	Fatalities and severe injuries	-60% *
	Cargo lost to theft and damage	-70% *

Targets for 2030: safety issues



Societal Need	Indicator	Guiding objective for 2030
Safety	Fatalities and Severe Injuries	-60%*
	Cargo lost to theft and damage	-70%*



PART I : PASSIVE SAFETY

PASSIVE AND ACTIVE SAFETY SYSTEMS

- Active safety: all the measures reducing the probability of occurrence of accidents
- Passive safety: Reactive measures that aims at reducing the severity of the injuries in case of crash (when it can not be avoided)
- Educational measures: Safety campaign against speed, driving under alcohol, drugs, etc.



PASSIVE AND ACTIVE SAFETY SYSTEMS



ACTIVE & PASSIVE SAFETY SYSTEMS

Vehicle safety system configuration diagram to be developed.



Steering column

- First attempt was the modification of the steering wheel and the steering column not to impact the driver
- In 1950ies, a massive steering wheel with a metal-horn rim connected to a steering column that was a rigid piece. So, in a frontal collision, the driver was effectively at the business end of a battering ram.
- Then, designers shrunk tailfins, engineers developed collapsible steering columns consisting of multiple parts. Rather than shooting toward the driver upon heavy impact, the column's sections compact like a telescope.





Seat belts





 The second factor of passive safety are the seat belts and its later developments like pretensioners





Airbags

- Airbags are mitigating the shocks of body parts (especially the head) against the interior part of the vehicle
- There is now an expansion of airbag types: frontal, side, heads and even external ones for pedestrian shocks









- By law, all new car models must pass certain safety tests before they are released on the market.
- Legislation provides a minimum statutory standard of safety for new cars.
- The aim of Euro NCAP is to encourage manufacturers to exceed these minimum requirements.







Crumble zones in modern structures of car body for improved safety



STRUCTURAL SAFETY ENHANCEMENTS





FRONTAL IMPACT

- Frontal impact test is based on that developed by European
 Enhanced Vehicle-safety
 Committee as basis for
 legislation, but impact speed has
 been increased by 8 km/h.
- Frontal impact takes place at 64kph, car strikes deformable barrier that is offset.



SIDE IMPACT

The second most important crash configuration is the car-to-car side impact. Euro NCAP simulates this type of crash by having a mobile deformable barrier (MDB) impacting the driver's door at 50 km/h. The injury protection is assessed by a side impact test dummy, in the driver's seat.



SIDE IMPACT

 Pole test: Approximately a quarter of all serious-to-fatal injuries in EU happen in side impact collisions. Many of these injuries occur when one car bumps into the side of another or into a fixed narrow object such as a tree or pole.



SIDE IMPACT

To encourage manufacturers to fit head protection devices, pole test may be performed, where such safety features are fitted. Side impact head or curtain airbags help to protect the head and upper torso by providing a padding effect and by preventing the head from passing through the window opening. In the test, the car tested is propelled sideways at 29kph into a rigid pole. The pole is relatively narrow, so there is a major penetration into the side of the car.



- After having improved the occupant protection, the legislator is now trying to improve the third party's injuries, in particular the pedestrians.
- This resulted in several measures
 - Face lift agreement
 - Modification of the car hood



- Pedestrian are weak users of the roads.
- Reducing the number of fatalities and injuries is a great challenge of sustainable roads







- EURO NCAP
 - A series of tests are carried out to replicate accidents involving child and adult pedestrians where impacts occur at 40kph. Impact sites are then assessed and rated fair, weak and poor. As with other tests, these are based on European Enhanced Vehicle-safety Committee guidelines



ACTIVE SAFETY SYSTEMS

- Why active safety systems?
 - The (on-board) passive safety systems have shown a lower pay-back than expected
 - In terms of saved lives if we compare to the extra mass that we pay for a given increase of safety
 - Antagonistic issue between the mass to increase the safety and the reduction of the mass to increase the fuel economy
 - Moreover the aggressive character of certain types of vehicles as the SUV
 - The human error is responsible for 75% to 90% of the road accident. Human error can not be reduced by passive safety systems.








Effect of mass reduction

- Following the CAFÉ (Corporate Average Fuel Economy) recommendation and other environmental constraints, there is great pressure to reduce the weight of cars.
- The reduction of the weight has a very negative impact on the safety:
 - In the USA, one estimates that a weight reduction of 50 kg would result in an increase of 10543 wounded persons on the road.
 - Moreover, studies show that the difference of mass between colliding vehicles is a great source of fatalities
 - For instance, Gabler & Fildes (SAE paper 1999-01-069) estimates that the probability of fatalities F1 and F2 in the two vehicles of mass M1 and M2 is related by a power law



Effect of mass reduction



Roel Boesenkool SMEA conference

 Generally one estimates that 10% of mass reduction results in an average reduction of 6% of the fuel consumption

Conflict between mass reduction and fuel consumption



 S. Hoffenson, P. Papalambros, M. Kokkolaras, M. Reed. An optimization approach to occupant safety and fuel economy in vehicle design. 8th World Congress on Structural and Multidisciplinary Optimization June 1 - 5, 2009, Lisbon, Portugal

 Following the statistics of the NHTSA (National Highway Transportation Safety Association) (1999) the probabilities of fatalities in a crash with a SUV or light duty vehicle is increased by 2 to 4 compared to a medium size car

Collision: Accord vs. Explorer



Scenario: offset crash, both vehicles move at 35mph

Crash test between an Audi Q7 and a Fiat 500 made by ADAC

https://www.youtube.com/watch?v=6pVF1Wr7GLQ



FIGURE 4. AGGRESSIVITY RANKING: LTVs vs CARS



Hollowell & Gabler, NHTSA paper 96-S4-O-01



Hollowell & Gabler, NHTSA paper 98-S3-O-01



Hollowell & Gabler, NHTSA paper 98-S3-O-01



Aggressivety of heavy vehicles

 Following the statistics of the NHTSA (National Highway Transportation Safety Association) (1999) the probabilities of fatalities in a crash with a SUV or light duty vehicle is increased by 2 to 4 compared to a medium size car





PART II : ACTIVE SAFETY

Active safety systems

- Active safety systems are all systems that aims at preventing the crash or reducing its severity before it happens.
- Examples of systems
 - Antilock Bracking System (ABS)
 - Traction Control Systems (TCS)
 - Vehicle Dynamics Control (VDC)
 - (Electronic Stability Program ESPTM)
 - Roll over detection
 - Electronically Controled Suspension (ECS)
 - Intelligent tyre

Why active system? Human errors

- Human errors is responsible for 75% of road accident for passenger cars and 80 to 90% for accident with duty vehicles.
- The reaction time of human people (average time is 0,75 sec) is the source of a dangerous situation for the vehicle and for the traffic.



If a warning signal was emitted 0,5 (1,0) sec before crash, it could avoid 30 to 60% (or 60 to 90 %) of the accidents !

Active safety: the targets



Active safety: the targets

- Rear-end crash (as well as frontal): 25 % (28%) of accidents
 - Measure of the field (or its variation) can give a warning scheme based on the time-to-collision
- Lane departing: 20% of accidents 36% of fatalities
 - Measure of the lane departing. Warning based on the lane crossing
- Lateral and back crash: 7% of accidents
 - Proximity detector (with a sonar sensor for instance). Warning based on the detection of object detection and time-to-collide
- Intersections: 30% of crashes
 - Wide detection using large angle sensors, intersection directions in order to identify the possible collisions

Warning system for rear-end collision

- Working principle:
 - Identify a target
 - Measure the distance, the rate of distance change, and the vehicle speed
 - Predict the vehicle trajectory
 - Warning algorithms based on
 - Time before collision
 - Estimation of the vehicle speed, the friction coefficient, the human reaction time (reaction, judgment).
- Weakness and difficulties:
 - Wrong warnings and noisy signals



Fig 3.11 ABS operation to stay at the peak braking coefficient.



- The ABS (Anti-lock Brake System) monitors the speed of each wheel to detect locking.
- When it detects the wheel locking, it releases braking pressure for a moment and enables the wheel to reaccelerate
- By a sequence of braking / releasing ABS provides optimum braking pressure to each wheel.

Fig. 3.10 Wheel speed cycling during ABS operation.



Fig. 3.54 Effect of skid on cornering force coefficient of a tire.



- By limiting the longitudinal slip, it preserves the lateral force capability and helps improving the ability of stopping the vehicle in stable conditions
- ABS generally reduces the braking distance but not always. The major contribution of ABS is to be able to keep the control of the car during braking maneuver even in turning conditions

The ABS system includes:

- Wheel speed sensors
- Pressure sensors
- An ECU system that will detect the locking and will manage the cycles of pressure increase and decrease
- A hydraulic valve that is able to connect the brake piston to hydraulic power source or to the return circuit





30 Years of Safe Braking with Bosch ABS



- The ESP system aims at insuring the control of the lateral dynamics of the vehicle in any circumstances
- One major commercial name ESP = Electronic Stability Program
- The Bosch ESP relies on the braking system to achieve the directional control of the vehicle and its stability
- The ESP is an evolution (or a revolution?) of former systems ABS, TCS and relies on these technologies. The ESP goes far beyond of the objectives of these systems.
- When the ESP function is on, the braking system priority is modified. When ESP intervenes, the fundamental functions of the braking systems (braking and stopping the vehicle) are put on the back to insure the stability of the vehicle

- ESC addresses the problem of skidding and crashes due to loss of control of vehicles, especially on wet or icy roads or in rollovers.
- Evaluation studies have shown that the fitment of ESC in cars can lead to substantial reductions in crashes, deaths and serious injuries.
 - A Swedish study in 2003 showed that cars fitted with ESC were 22% less likely to be involved in crashes than those without. There were 32% and 38% fewer crashes in wet and snowy conditions respectively.
 - In Japan, a study showed that electronic stability reduced crash involvement by 30-35%
 - In Germany, one study indicated a similar reduction while another showed a reduction in 'loss-of-control' crashes from 21% to 12%.



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Nowadays the ESC

penetration of the

market for new

vehicles: 55%

shows a high

- The operation of ESP plays with an independent braking of the four wheels. Example:
 - Braking on the rear wheel to control the under steer
 - Braking on the front wheel to counteract an over steer



- For a maximum efficiency, the ESP operates with independent wheel braking, but also with the engine electronic control unit to accelerate or reduce the torque under the driven wheels.
- The ESP has two complementary strategies:
 - Differential braking on independent wheels
 - Modulation of the torque on the driven wheels
- The ESP helps to maintain the vehicle on the road within the capability of physics
 - Reduction of the roll-over
 - Reduction of the accident probability
 - Improving the safety by providing an active support to the driver.

Example 1: right left cornering sequence

Road with a high friction grip $\mu = 1$ The driver is not braking $V_{init} = 144$ km/h

Bosch (1999) Pages 207-208





Lane change during panic stop at

 $v_0 = 50 \text{ km/h}$ and $\mu_{\text{HF}} = 0.15$ (black ice)



Example 2 : Lane change with panic stop

Introduction

50 km/h

+300°

Vehicle velocity

Steering-wheel angle

-300°

Yaw rate

Float angle

-16

0

 $+16^{\circ}$

+40 °/s

ABS versus ESP

Slippery road μ =0.15 $V_{init} = 50 \text{ kph}$

Bosch (1999) Pages 209-210

Introduction

Example 3 : Rapid steering and counter steering inputs

Road covered by snow μ =0.45 No braking V_{init} = 72 km/h

Bosch (1999) Pages 210-212 Curves for dynamic response parameters for rapid steering and countersteer inputs with increasing steering-wheel angles

Increased braking force



Curves for dynamic response parameters for rapid steering and countersteer inputs with increasing steering-wheel angles

1 Vehicle without ESP, 2 Vehicle with ESP.



Introduction

Example 4 : Cornering under braking / accelerating

Cornering under braking, constant steering-wheel angle

1 Vehicle with USP 2 Vehicle with ESP

Cornering under acceleration

Here Braking-force increase



Curve wit a reducing radius (as in highway exit) Constant speed Bosch (1999) Pages 212-213



Example 4 : Cornering under braking / accelerating

Circular test Road with a high grip μ =1 Radius R=100m Increasing speed up to the critical speed V=98 km/h

Bosch (1999)

Fig 11 Pages 213

Above: Without ESP the vehicle breaks into a slide. Below: ESP keeps the vehicle on track.



Working principle of ESP



Instrumentation of the ESP



Microsystems & automobile



Thursday, 18 May 2000 Microelectromechanical Systems (MEMS) Short Course © M. Adrian Michalicek, 2000 Slide 8

The Future of Safety: ADAS

The future is Advanced Driver Assistance Systems or ADAS, are systems that aims to help the driver in its driving process. When designed with a safe Human-Machine Interface, it should increase car safety and more generally road safety.



Source www.conti-online.com

ADAS

- Examples of ADAS systems are:
 - In-vehicle navigation system with typically GPS and TMC for providing up-to-date traffic information
 - Adaptive cruise control (ACC)
 - Lane departure warning system
 - Lane change assistance
 - Collision avoidance system (Precrash system)
 - Night Vision
 - Adaptive light control
 - Pedestrian protection system
 - Traffic sign recognition
 - Blind spot detection
 - Driver drowsiness detection
 - Vehicular communication systems...

ADAS: examples



Emergency Brake Assist

The Emergency Brake Assist reacts when the driver does not realize the danger.

Adaptive Cruise Control:

ACC offers stress free driving with the traffic flow, while maintaining proper speed and distance to the traffic ahead.



Source conti www.conti-online.com




Blind Spot Detection:

BSD warns the driver when there are vehicles in the blind spot of the side-view mirror. Lane Departure Warning / Lane keeping System: LDW / LKS provides the driver with warnings to protect him from unintentionally leaving the lane.



Source conti www.conti-online.com

ADAS: examples



Intelligent Headlamp Control: Safer and less tiring driving through optimized vision at night.

Speed Limit Monitoring:

Speed Limit Monitoring ensures that the current speed limit is displayed for the driver on an ongoing basis.



Source conti www.conti-online.com

ADAS: examples



eHorizon:

The demands towards the performance of navigation systems grow. A fast, reliable and economical route calculation will be an essential quality characteristic.

Source conti www.conti-online.com

Autonomous vehicles



2020









Autonomous vehicles

 One key element of autonomous vehicles is the battery of sensors and in the fusion of the various information items



Figure 2 Several driver-assistance systems are currently using radar technology to provide blind-spot detection, parking assistance, collision avoidance, and other driver aids (courtesy Analog Devices).

Autonomous vehicles

 Autonomous electric vehicles offers great opportunity for innovative solution in the urban driving





ADAS: Vehicular communication systems



INTELLIGENT TRANSPORTATION SYSTEMS





PART III : INFRASTRUCTURES

- In a car accident, there is three types of collisions that intervene sequentially:
 - 1/ Collision vehicle to obstacle: the vehicle is deformed and decelerated. The kinetic energy of the vehicle is dissipated.
 - 2/ Collision between the passenger and the vehicle or passenger to passenger. The passenger body can touch the steering wheel, the board, the windshield, etc.
 - 3/ Internal collisions of internal parts of body of the passenger. The damage of organs is due to internal collisions, high stresses in bones and tissues

- Internal damages due to decelerations and shocks is the topics of biomechanics
- The resistance of body to deceleration and shocks are taken into account by empirical laws like Head Impact Criteria (HIC)
- However, we have little lever arms to reduce directly these damages



Lobes of the Brain

Sketch by Abhishake Sharma



- The collisions between the passengers and the vehicle surfaces or between the passengers may lead to important body damages.
- The contact involves decelerations in body organs, efforts in bones and tissues
- To avoid or reduced the severity of these contacts, several systems have been tailored:
 - Seat belts
 - Seat belts pretensioners
 - Airbags









Collision vehicle to obstacle

- The deformation of the compartment is dangerous so that the occupant can be prisoner of the vehicle.
- The major parameters to mitigate the crash severity are
 - The energy absorption capability of the vehicle structure → crushing zones to dissipate the energy

- The resistance to deformation of the vehicle frame around the passengers to protect the occupants

- In case of high severity crashes, the energy absorption is not sufficient, and the obstacle capacity to dissipate energy is essential to reduce the decelerations and the reduce the body injuries.
- This is the key role of restraint systems like: side rails, bumpers, etc.





- Infrastructure specifications are ruled by EN1317 norm.
- Mainly the design of the safeguards is
 - To reduce the severity of the deceleration of the vehicle
 - To control the depth of the pocket in the crushed zone
 - To absorb as much as possible of the kinetic energy and to reduce the exit velocity of the vehicle.
- Design of safety infrastructure calls for a combined investigations including experimental testing and simulations as in vehicle crashworthiness











http://www.lier.fr/Catalogue/Produit-Norme-europeenne-EN-1317-2.html



Simulations of crash test using fast dynamics software tools





Master Thesis by E. Michel, 2008

Master Thesis by X. Ernst, 2008